



Department of Geography and Earth Sciences

## WRM 625-Hydrological Modeling

Lecture 4- Time Series Analysis and Stochastic Modeling

Test 1: Thursday, 1/10/2020, 10.00am-11.00am

# Introduction

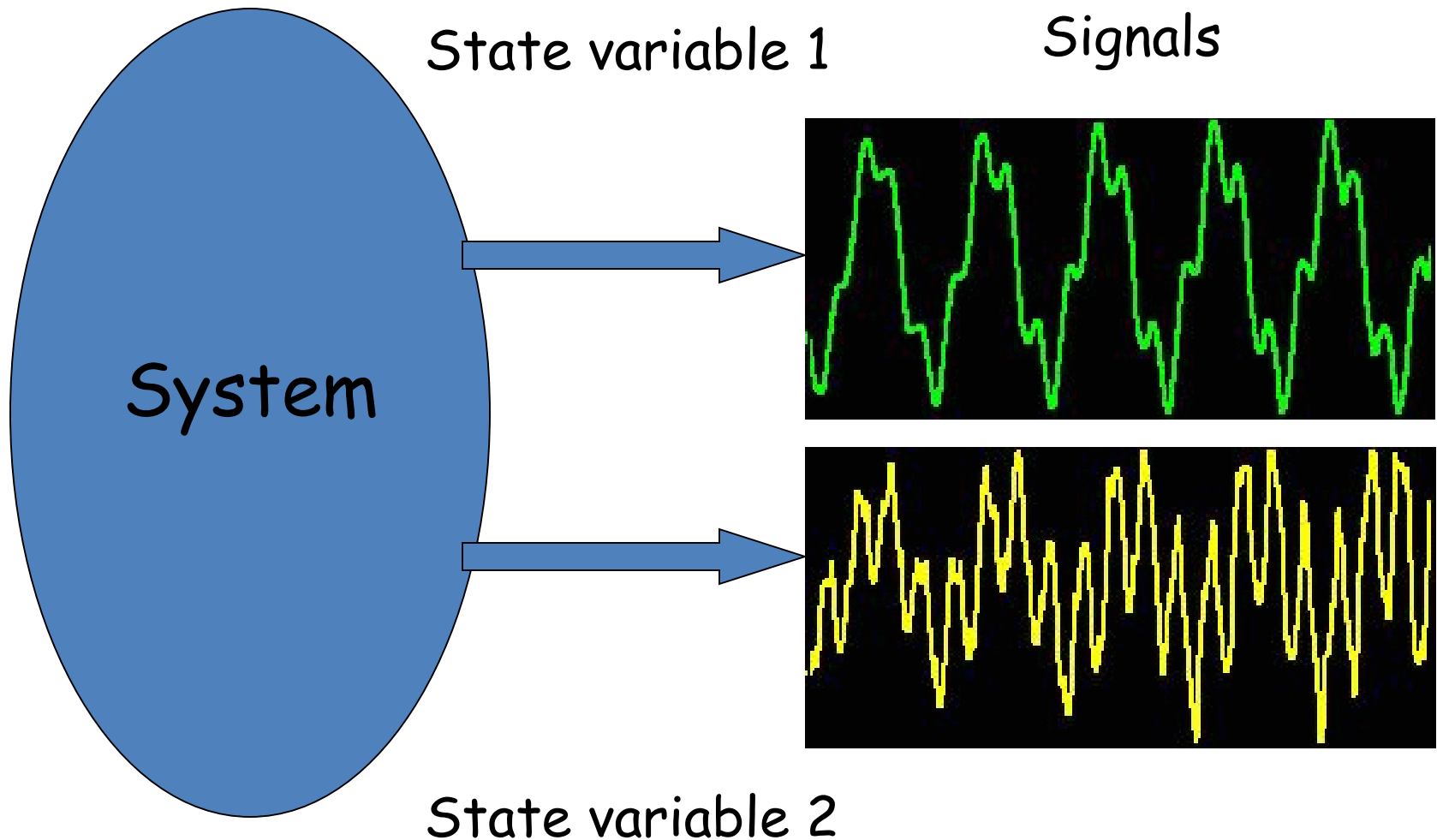
- Whatever is going on around us are processes occurring in certain systems. Some obvious examples are:
  - ✓ the change of weather (system: Earth atmosphere)
  - ✓ the change of illumination during the day (system: Earth atmosphere)
- In lay terms: **process** is the change in time of the state of the system.
- Note: the **state of the same system** can be characterized by one or several variables.

# Introduction

Examples of variables:

- Current weather at Chancellor College can be characterized by air temperature, humidity, wind velocity, atmosphere pressure, etc.
- One may record and observe the change in time of several, or of just one variable characterizing the system state.
- The recorded dependence of some variable in time is also called a **realization**.

# System, Process and Signal



# Time Series

- **Time series:** a collection of observations of state variables made sequentially in time.
- **Sequential generation:** means they are dependent to each other such that we do NOT have random sample.
  - ✓ We assume that observations are equally spaced in time.
  - ✓ We also assume that closer observations might have stronger dependency.
- **Univariate (bivariate, multivariate) time series:** collection of observations of one (two, several) state variables, each made at sequential time moments.

Note: the order of observations is important!

# Time Series

## Notations

- continuous signal  $a(t)$
- time series  $a(t_i)=a(i\Delta t)=a_i, i=1,2,\dots,L$
- sampling step  $\Delta t$
- length of time series  $L$
- sampling frequency  
 $f_s=1/\Delta t$

## Synonyms:

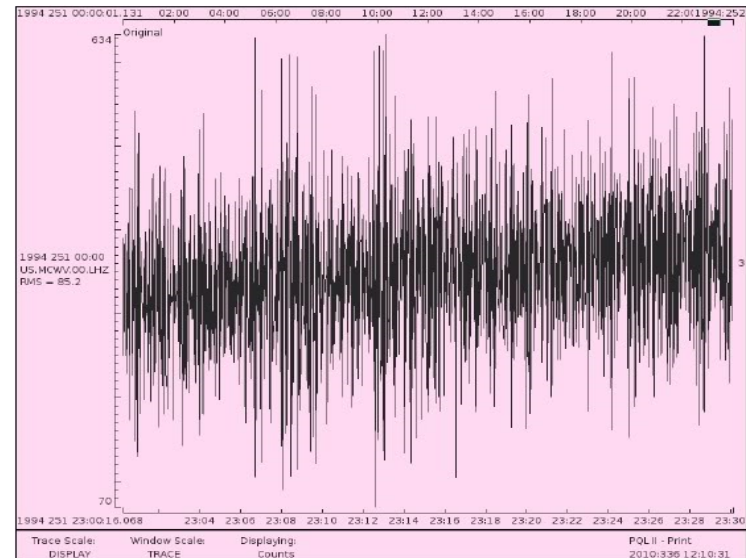
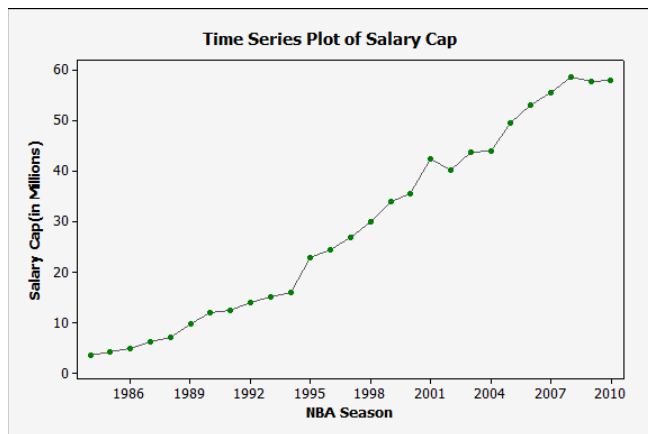
- Time series, (experimental) data, sampled signal, discretize signal
- Sampling rate (step), discretization rate (step)
- Time Series Analysis, Data Analysis, Signal Processing, Data Processing

## Note:

Mathematically, “time series” is not a SERIES, but a SEQUENCE!

# Time series

- Discrete time series is one in which the set  $T_0$  at which observations are made is a discrete set.
- Continuous time series are obtained when observations are recorded continuously over some time interval.



# How time series can arise

1. Given a continuous signal, one can sample its values at equal time intervals. **Example:** river discharge
2. The value of the state variable aggregates (accumulates) during some time interval. **Example:** daily rainfall
3. Some processes are inherently discrete.  
**Example:** amount of rainfall recorded per hour

## Kinds of processes

- Random (stochastic) process
- Deterministic process
- Mixed



# Aims of Time Series Analysis

## 1. Description

Describe (characterize) a generating process using its time series.

## 2. Explanation

If time series is bi- or multi-variate, then it may be possible to use variations in one variable to explain the variations in another variable.

## 3. Prediction (forecasting)

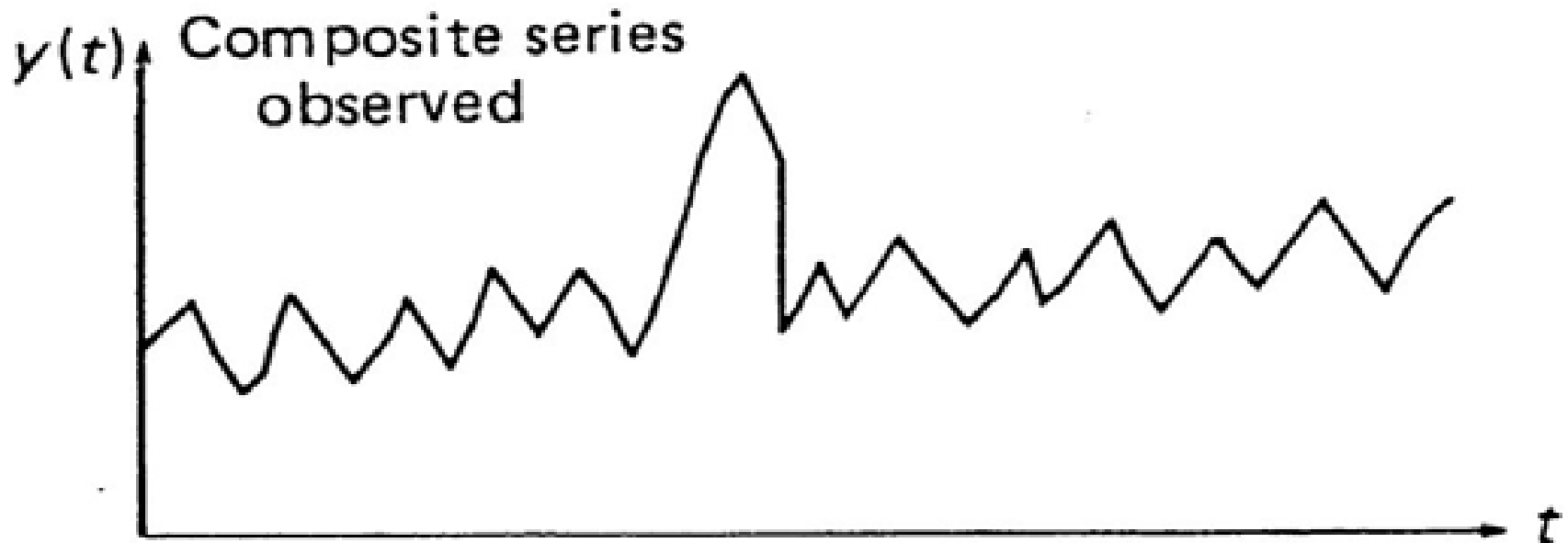
Use the knowledge of the past of the time series to predict its future.

## 4. Control

To change deliberately the properties of the process by influencing it and observing the changes introduced by our intervention.

- One can then learn to make the needed effort to achieve control.

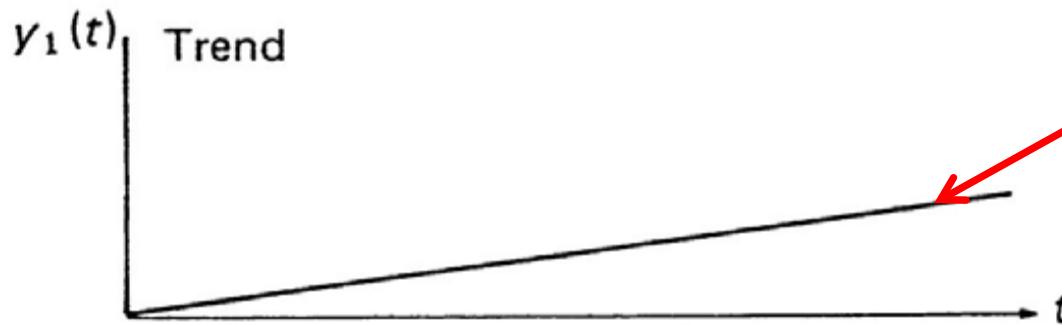
# Example



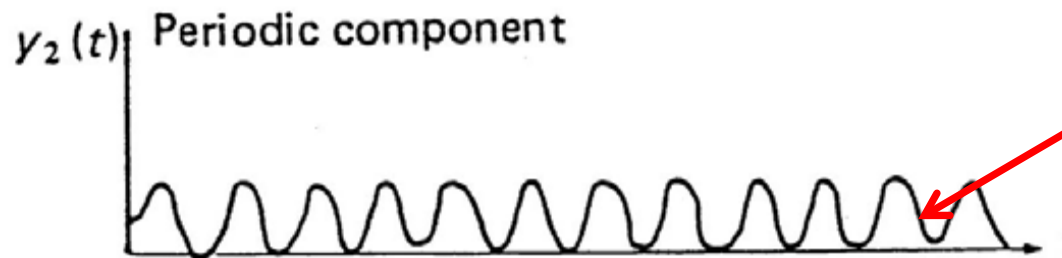
A Series of Observations ( $y(t)$ ) changing with time ( $t$ )

# Example

Three discernible features in the pattern of the observations.



Upward linear trend



Periodic component



Rare Catastrophic event, not possible or easy to define

# Example

- $y_4(t)$ - a hidden feature of the series is the random stochastic component representing an irregular but continuing variation within the measured values and may have some persistence.
  - ✓ chaotic noisy residuals left overs after all three have been accounted for.
- It may be due to:
  - instrumental or observational sampling errors
  - random unexplainable fluctuations in a natural physical process.
- A time series is said to be a random or stochastic process if it contains a stochastic component.
- Most Hydrologic time series may be thought of as stochastic processes since they contain both deterministic and stochastic components

# Times series

- Can be expressed as

$$y(t) = y_1(t) + y_2(t) + y_3(t) + y_4(t)$$

Deterministic components,  
easier to identify or  
quantify

Stochastic or Random  
components, with  
persistence effects, less  
easier to identify or  
quantify

# Properties of time series

- Mean

- ✓ Sample estimation
- ✓ Population notation

$$E(X_t) = \overline{X} = \frac{1}{n} \sum_{t=1}^n X_t$$
$$\mu$$

- Variance

- ✓ Sample estimation
- ✓ Population notation

$$S^2 = \frac{1}{n-1} \sum_{t=1}^n (X_t - \overline{X})^2$$
$$\sigma^2$$

- Co-variance

$$Cov(X_t, X_{t+L}) = \frac{1}{n-L} \sum_{t=1}^n (X_t - \overline{X})(X_{t+L} - \overline{X})$$

Where L is the time lag.

# Stationary time series

- A time series is stationary if the sample statistics are not functions of the timing or the length of the sample
- Can be stationary to the second moment, weakly stationary or strongly stationary.

$$E(X_t) = \mu$$

$$Var(X_t) = \sigma^2$$

$$Cov(X_t, X_{t+L}) = \lambda_L$$

- Basic assumption in time series as all the other components can be removed leaving them stationary.

# Non-stationary time series

- A time series is non-stationary if the sample statistics are dependent on the *timing* or the *length* of the sample.
- If series have a definite trend

$$E(X_t) = \mu_t$$

$$Var(X_t) = \sigma_t^2$$

$$Cov(X_t, X_{t+L}) = \lambda_{L,t}$$



# White noise time series

- For a stationary times series, if the process is purely random and stochastically independent, the time series is called a white noise series
- Represented as

$$E(X_t) = \mu$$

$$Var(X_t) = \sigma^2$$

$$Cov(X_t, X_{t+L}) = 0 \text{ for all } L \neq 0$$

# Gaussian time series

- A process (not necessarily stationary) of which all random variables are normally distributed, and of which all simultaneous distributions of random variables of the process are normal.
- A Gaussian random process that is weekly stationary, it is also strictly stationary, since the normal distribution is completely characterised by its first and second order moments

# Analysis of Hydrologic Time Series

- Rainfall and river flow data are ideal for time series analysis.
- Extremes frequency analysis.
- Synthesizing long time series from short records
- Evaluation of data quality, outliers etc.
- Cross correlation to understand hydrological processes.
- Identification of the several components of a time series.
- Mathematical description (modelling) different components identified.

# Analysis of Hydrologic Time Series

- Suppose you have a hydrological time series  $X_t$

$$X_1, X_2, X_3, \dots, X_t, \dots$$

- Structure of  $X_t$  can be represented as

$$X_t \Leftrightarrow [T_t, P_t, E_t]$$

Trend Component,  
Deterministic

Periodic Component,  
Deterministic

**Basic model for time  
series analysis**

Stochastic Component,  
random with self  
correlated persistence

# Aims of time series analysis

- (1) Description and understanding of the mechanism
- (2) Monte-Carlo simulation-repeated random sampling to solve deterministic problems
- (3) Forecasting future evolution

# Trend component

- Can be caused by
  - long-term climatic change or, in river flow, by gradual changes in a catchment's response to rainfall owing to land use changes.
- Sometimes, the presence of a trend cannot be readily identified

# Methods of trend identification

- Parametric and non-Parametric approaches
- Mann (1945) and Kendall (1975)
- Mann-Kendall test
  - Non-Parametric test (Distribution free)
  - Uses the raw (un-smoothed) hydrologic data to detect possible trends.
  - The Kendall statistic was originally devised by Mann (1945)
  - Statistic Approaches normal when
  - Only calculates the significance and direction of trend  $n \geq 8$

# Linear regression method

- Can be used to identify if there exists a linear trend in a hydrologic time series.
- Fitting a linear regression equation with the time  $t$  as independent variable and the hydrologic data and  $Y$  as dependent variable

$$y = \alpha + \beta.t$$

testing the statistical significance of the regression coefficient  $\beta$ .



# Models for trend

- Linear trend

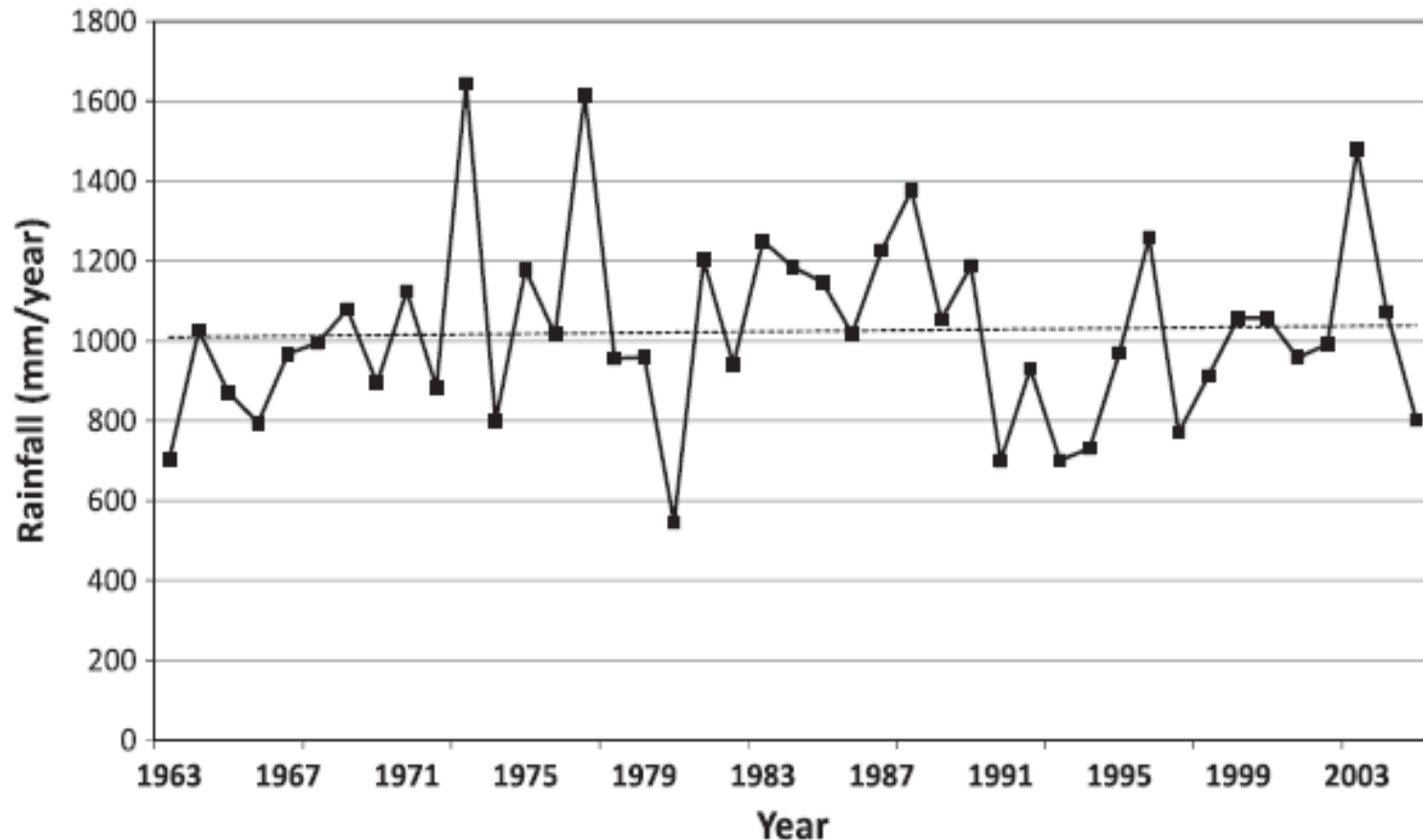
$$T_t = a + bt$$

- Non-Linear trend

$$T_t = a + bt + ct^2 + dt^4 + \dots$$

- Coefficients  $a$ ,  $b$ ,  $c$ ,  $d$ , ... are usually evaluated by least-squares fitting
- Number of terms restricted by phenomena, least number of parameters desired

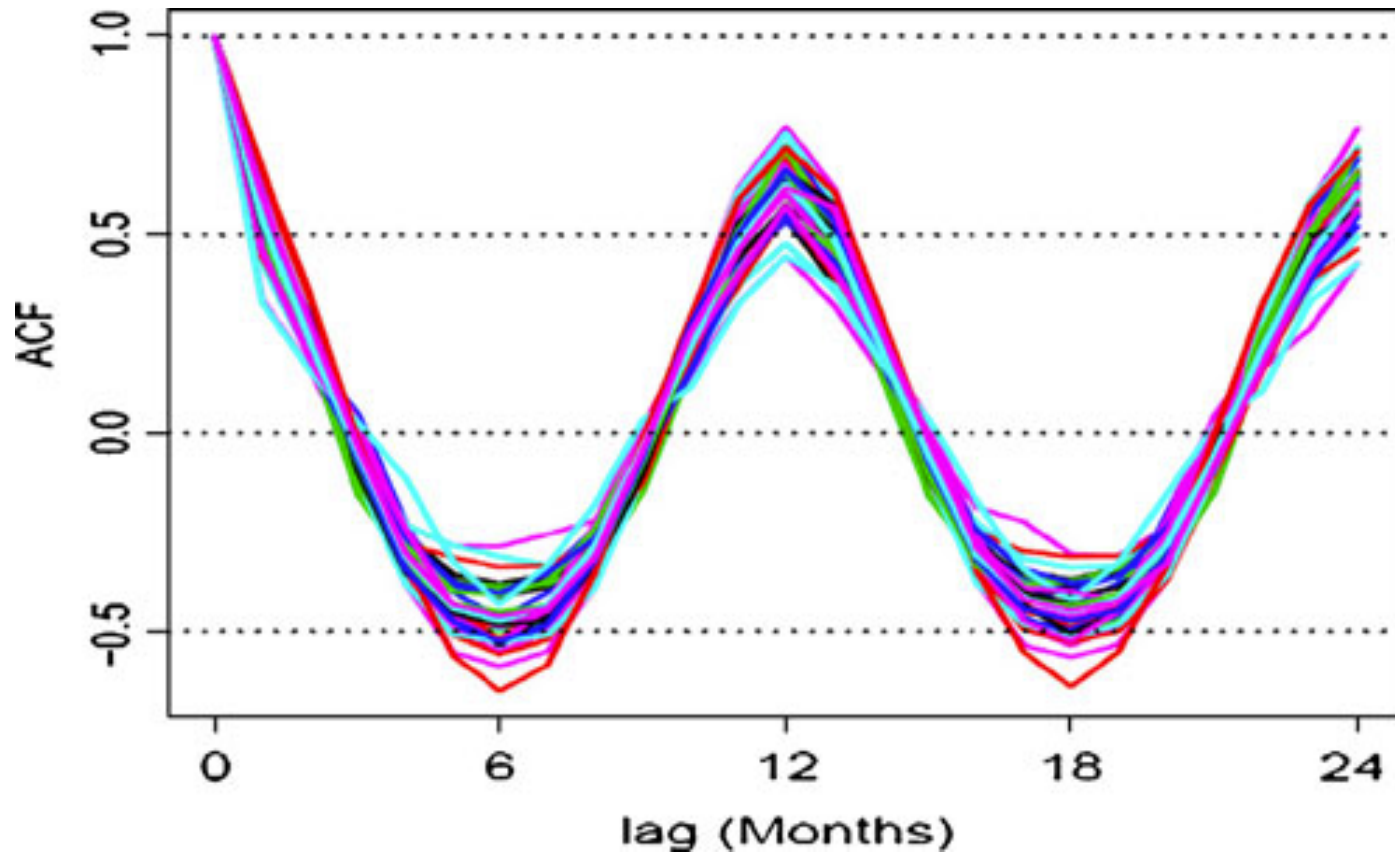
# Periodic component



Annual series- No periodic component

Source: Chimtengo, Ngongondo et al. 2014, JPCE

# Periodic component



Monthly series- periodic component, seasonal effects

Source: Ngongondo et al. 2011, Theor App. Clim.

# Periodic component

- The existence of periodic components may be investigated quantitatively by

- (1) Fourier analysis,
- (2) spectral analysis, and
- (3) Wavelet analysis
- (4) autocorrelation analysis- widely used in hydrology

# Autocorrelation analysis

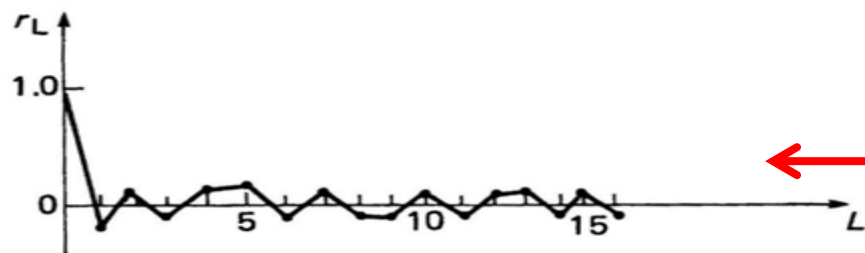
- Two steps
  - calculating the autocorrelation coefficients and
  - testing their statistical significance
- For a time series  $X_t$ , the autocorrelation coefficient  $r_L$  between  $X_t$  and  $X_{t+L}$  are calculated and plotted against values of  $L$  for all pairs of data  $L$  time units apart in the series.

$$r_L = \frac{1}{n-L} \sum_{t=1}^{n-L} (X_t - \bar{X})(X_{t+L} - \bar{X}) / \frac{1}{n} \sum_{t=1}^n (X_t - \bar{X})^2$$

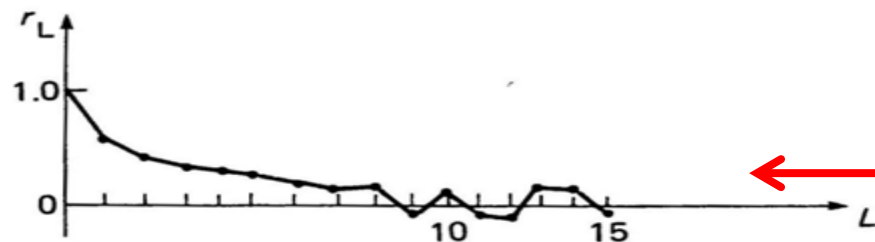
- $L$  is normally taken up to  $n/4$

# Autocorrelation analysis

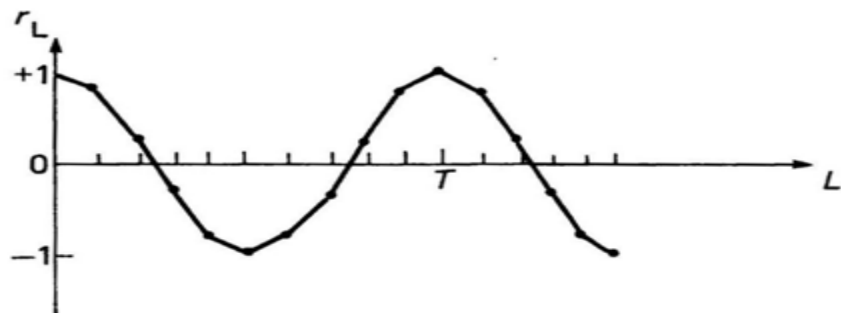
- Plot on a correlogram  $R$  vs  $L$



(a) Random, independent noise



(b) Autoregressive, Markov process



(c) Pure sine wave

- If  $L = 0$ ,  $r_L = 1$ . That is, the correlation of an observation with itself is one.

- If  $r_L \approx 0$  for all  $L \neq 0$ , the process is said to be a purely random process. This indicates that the observations are linearly independent of each other.

Deterministic  $r_L \neq 0$  for all  $L \neq 0$

If  $r_L \neq 0$  for some  $L \neq 0$ , but after  $L > \tau$ ,  $r_L \approx 0$  system is random

# Modelling of periodic component

- A periodic function  $P^t$  is a function such that

$$P_{t+T} = P_t$$

- For all  $t$  and  $T$  is called the period i.e. smallest time it takes to complete one cycle
- Also for all integer  $n$   $P_{t+nT} = P_t$
- The frequency is defined as the number of periods per time-unit:

$$Frequency = \frac{1}{Period}$$

End of Lecture 4